

Cheat sheet

SI-Units

- Base Units

Dimension	T	L	M	θ	N	I	I_v
Unit	s	m	kg	K	mol	A	cd

- Derived units

Hz	s^{-1}
N	$kg\ m\ s^{-2}$
Pa	$N\ m^{-2}$
J	N m
W	$J\ s^{-1}$

Dimensionless numbers

Reynold number	Re	$\frac{vL}{\nu}$
Froude number	Fr	$\frac{v}{\sqrt{gh}}$
Shallowness parameter	ϵ	$\frac{H}{L}$
Peclet number	Pe	$\frac{Lv}{\alpha}$
Prandtl number	Pr	$\frac{\nu}{\alpha}$
Stefan number	Ste	$\frac{c_p \Delta T}{h_m}$ h_m : latent heat of melting
Strouhal number	Str	$\frac{fL}{v}$
Mach number	Ma	$\frac{v}{c}$
Lewis number	Le	$\frac{\alpha}{D}$

Miscellaneous

1. Shape factor

$$\alpha = \frac{\overline{u^2}}{\overline{u}^2}, \text{ where } \overline{*} = (1/h) \int_b^s * dz$$

2. Decomposition of the velocity profile

$$\mathbf{v}(\mathbf{x} + \mathbf{r}) = \mathbf{v}(\mathbf{x}) + \mathbf{w} \times \mathbf{r} + \mathbf{D} \cdot \mathbf{r}$$

$$\text{where } \mathbf{w} = \frac{1}{2} \nabla \times \mathbf{v}, \mathbf{D} = \frac{1}{2} (\nabla \mathbf{v} + \nabla \mathbf{v}^T), \mathbf{W} = \frac{1}{2} (\nabla \mathbf{v} - \nabla \mathbf{v}^T)$$

3. Cylindrical coordinate transformation rules

$$\begin{aligned} \nabla f &= \frac{\partial f}{\partial r} \vec{e}_r + \frac{1}{r} \frac{\partial f}{\partial \theta} \vec{e}_\theta + \frac{\partial f}{\partial z} \vec{e}_z, \\ \nabla \cdot \vec{A} &= \frac{1}{r} \frac{\partial}{\partial r} (r A_r) + \frac{1}{r} \frac{\partial A_\theta}{\partial \theta} + \frac{\partial A_z}{\partial z} \\ \nabla \times \vec{A} &= \left(\frac{1}{r} \frac{\partial A_z}{\partial \theta} - \frac{\partial A_\theta}{\partial z} \right) \vec{e}_r + \left(\frac{\partial A_r}{\partial z} - \frac{\partial A_z}{\partial r} \right) \vec{e}_\theta + \frac{1}{r} \left(\frac{\partial}{\partial r} (r A_\theta) - \frac{\partial A_r}{\partial \theta} \right) \vec{e}_z \end{aligned}$$

4. Material derivative

$$\frac{D}{Dt} f = \partial_t f + \mathbf{v} \cdot \nabla f$$

5. Bernoulli equation

$$\frac{p}{\rho} + \frac{v^2}{2} + gz = \text{const. along streamline}$$

6. Error function

$$\begin{aligned} \text{erf}(x) &:= \frac{2}{\sqrt{\pi}} \int_0^x e^{-y^2} dy, \quad \text{erfc}(x) := 1 - \text{erf}(x) \\ \partial_x \text{erf}(Cx) &= \frac{2}{\sqrt{\pi}} C e^{-(Cx)^2}, \quad \partial_x \text{erfc}(Cx) = -\frac{2}{\sqrt{\pi}} C e^{-(Cx)^2} \end{aligned}$$

7. Thermal diffusivity

$$\alpha = \frac{\kappa}{\rho c_p}$$

Physical principles

1. Material symmetry

$$\hat{\sigma}^{(\zeta)}(*) = \hat{\sigma}^{(\eta)}(*P).$$

2. Material Isotropy

$$\hat{\sigma}(F) = \hat{\sigma}(V \cdot Q) = \hat{\sigma}(V \cdot Q \cdot P) = \hat{\sigma}(V \cdot Q \cdot Q^T) = \hat{\sigma}(V)$$

3. Material objectivity

$$\sigma^{(y)} = Q \cdot \sigma^{(x)} \cdot Q^T$$

4. Galilean invariance

$$\zeta = \mathbf{x} - \mathbf{v}t$$

Mathematical models

1. Mass and momentum balance

$$\begin{aligned}\partial_t \rho + \nabla \cdot (\rho \mathbf{v}) &= 0 \\ \partial_t (\rho \mathbf{v}) + \nabla \cdot (\rho \mathbf{v} \otimes \mathbf{v}) &= -\nabla p + \nabla \cdot \boldsymbol{\tau} + \rho \mathbf{b}\end{aligned}$$

2. Incompressible Euler

$$\begin{aligned}\nabla \cdot \mathbf{v} &= 0 \\ \partial_t \mathbf{v} + \mathbf{v} \cdot \nabla \mathbf{v} &= -\frac{1}{\rho} \nabla p + \mathbf{b}\end{aligned}$$

3. Incompressible Navier-Stokes

$$\begin{aligned}\nabla \cdot \mathbf{v} &= 0 \\ \partial_t \mathbf{v} + \mathbf{v} \cdot \nabla \mathbf{v} &= -\frac{1}{\rho} \nabla p + \nu \Delta \mathbf{v} + \mathbf{b}\end{aligned}$$

4. Incompressible Navier-Stokes in cylindrical coordinates

$$\begin{aligned}\frac{\partial u_r}{\partial t} + (\vec{u} \cdot \vec{\nabla}) u_r - \frac{u_\theta^2}{r} &= -\frac{1}{\rho} \frac{\partial p}{\partial r} + \nu \left(\nabla^2 u_r - \frac{u_r}{r^2} - \frac{2}{r^2} \frac{\partial u_\theta}{\partial \theta} \right) \\ \frac{\partial u_\theta}{\partial t} + (\vec{u} \cdot \vec{\nabla}) u_\theta + \frac{u_r u_\theta}{r} &= -\frac{1}{\rho r} \frac{\partial p}{\partial \theta} + \nu \left(\nabla^2 u_\theta + \frac{2}{r^2} \frac{\partial u_r}{\partial \theta} - \frac{u_\theta}{r^2} \right) \\ \frac{\partial u_z}{\partial t} + (\vec{u} \cdot \vec{\nabla}) u_z &= -\frac{1}{\rho} \frac{\partial p}{\partial z} + \nu \nabla^2 u_z \\ \frac{1}{r} \frac{\partial}{\partial r} (r u_r) + \frac{1}{r} \frac{\partial u_\theta}{\partial \theta} + \frac{\partial u_z}{\partial z} &= 0\end{aligned}$$

5. Heat equation

$$\partial_t T + \nabla \cdot (T \mathbf{v}) = \alpha \Delta T$$

6. Incompressible Navier-Stokes-Boussinesq-Fourier

$$\begin{aligned}\nabla \cdot \mathbf{v} &= 0 \\ \partial_t \mathbf{v} + \mathbf{v} \cdot \nabla \mathbf{v} &= -\frac{1}{\rho_0} \nabla (p - \rho_0 g z) + \nu \Delta \mathbf{v} - \mathbf{g} B (T - T_0) \\ \partial_t (\rho c_p T) + \nabla \cdot (\rho c_p T \mathbf{v}) &= \nabla \cdot (\kappa \nabla T) + \mathbf{S}\end{aligned}$$

Constitutive and closure relations

1. Newtonian fluid

$$\boldsymbol{\tau} = \lambda (\nabla \cdot \mathbf{v}) \mathbf{I} + \eta (\nabla \mathbf{v} + \nabla \mathbf{v}^T),$$

2. Hooke's law

$$\boldsymbol{\sigma} = \lambda \text{tr}(\mathbf{D}) \mathbf{I} + 2\mu \mathbf{D},$$

3. Boussinesq approximation

$$\rho = \rho_0 (1 - B(T - T_0))$$

4. Stefan condition

$$\rho_s L \partial_t X_m(t) = -\kappa \partial_x T(X_m^-(t), t) + \kappa \partial_x T(X_m^+(t), t)$$

Integration

1.

$$\int \exp(kx) dx = \exp(kx) + C$$

2.

$$\int x \exp(kx) dx = \exp(kx)(kx - 1)/k^2 + C$$